

**Part number:** **SSP-51<sup>®</sup>** 

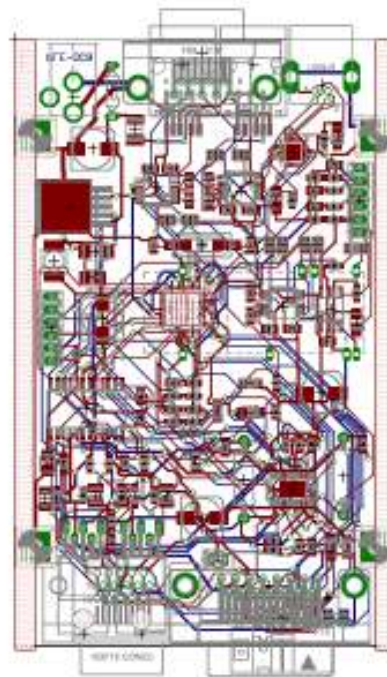
The **SSP-51** controller is intended as a **RoHs** compliant replacement for any stepper Controller

<b>Stepper controller:</b>	Single axis miniaturized controller for laboratory and industrial applications.
<b>Control loops:</b>	Available but not standard. Position, velocity acceleration
<b>Parameters control:</b>	Position, velocity, acceleration, torque. Adjustable "on the fly".
<b>Computer Interface:</b>	Standard RS-232 or <b>USB</b> . Also analog control and position display.
<b>Resolution:</b>	Down to 0.04mm depending on the motor used.
<b>Networkable:</b>	Up to 7 boards can be controlled from one PC with one Power Supply
<b>Inputs and Outputs:</b>	Digital and analog inputs and outputs for conversions and data acquisition.
<b>Power requirements:</b>	Max. 30VDC at 5A.
<b>Available options:</b>	Up to 7 boards networked, <b>Joystick</b> , Analog drive output, Wireless interface.
<b>Software:</b>	Terminal. LabView Drivers and DEMO software.
<b>Recommended actuator:</b>	SuprMike <sup>®</sup> , LDC-25, LDC-50.
<b>Dimensions:</b>	OEM size 4"x 3". Also available other board sizes and packages.

**No external amplifier is needed to control motors of any size up to 30V and 5Amps.**



Photo (OEM version)



Layout

The **VGA** type connector pin-out is listed below:

<b>Pin 1 - 2</b>	A – A'
<b>Pin 3 - 4</b>	B – B'
<b>Pin 5, 6, 7,</b>	NC
<b>Pin 8</b>	+5V for Limit switches
<b>Pin 9</b>	Negative limit switch (optional)
<b>PIN 13, 15</b>	GND
<b>Pin 11</b>	Min STOP or Home reference
<b>PIN 12</b>	Min deceleration
<b>PIN 14</b>	Max deceleration
<b>PIN 15</b>	Max. STOP